

```

//Holden Sandlar
//Multidisciplinary Senior Design

//Reads from RTC over I2C and displays the current time on four seven-segment displays

#include "Wire.h"
#include <stdio.h>
#include <stdlib.h>
#define DS1307_I2C_ADDRESS 0x68 //RTC I2C address

//SDA is on Arduino Pin A4
//SCL is on Arduino Pin A5

#define clk 12 //CLK out to shift registers
#define rst 8 //RST out to shift registers

#define MI_LO 5 //Minute Low digit on Shift register attached to arduino pin 5
#define MI_HI 4 //Minute high digit on shift register attached to arduino pin 4
#define HR_LO 3 //Hour low digit on shift register attached to arduino pin 3
#define HR_HI 2 //Hour high digit on shift register attached to arduino pin 2

// 1          2 :          3          0
// ^ hour high ^ hour low   ^ minute high ^ minute low

//Arduino Wire library was updated.. define I2C_READ/WRITE correctly for the version being used:
#if defined(ARDUINO) && ARDUINO >= 100 // Arduino v1.0 and newer
    #define I2C_WRITE Wire.write
    #define I2C_READ Wire.read
#else // Arduino Prior to v1.0
    #define I2C_WRITE Wire.send
    #define I2C_READ Wire.receive
#endif

//Variables for storing R/W values to/from RTC:
byte second, minute, hour, dayOfWeek, dayOfMonth, month, year;
byte zero;

//Digit map -- this is a map of which bits need to be turned on to display a given number on
the 7-segment
//Order of bits (which represent segments) is A, B, C, D, E, F, G
int digit_map [10][7] = {
    { 1, 1, 1, 1, 1, 1, 0 }, //0
    { 0, 1, 1, 0, 0, 0, 0 }, //1
    { 1, 1, 0, 1, 1, 0, 1 }, //2
    { 1, 1, 1, 1, 0, 0, 1 }, //3
    { 0, 1, 1, 0, 0, 1, 1 }, //4
    { 1, 0, 1, 1, 0, 1, 1 }, //5
    { 1, 0, 1, 1, 1, 1, 1 }, //6
    { 1, 1, 1, 0, 0, 0, 0 }, //7
    { 1, 1, 1, 1, 1, 1, 1 }, //8

```

```

    { 1, 1, 1, 0, 0, 1, 1 }, //9
};

void setup()
{
    Serial.begin(57600); // For DEBUG

    Wire.begin(); //Start I2C connection (2-wire interface)

    //Define outputs:
    //CLK, RST, Input to each shift register
    pinMode(clk, OUTPUT); //active high
    pinMode(rst, OUTPUT); //active low

    pinMode(HR_HI, OUTPUT); //Hour high digit
    pinMode(HR_LO, OUTPUT); //Hour low digit
    pinMode(MI_HI, OUTPUT); //Minute high digit
    pinMode(MI_LO, OUTPUT); //Minute low digit

    digitalWrite(clk, LOW); //Set clock low
    zero = 0x00; //Will be used to reset the RTC internal pointer
    clear_shift_regs(); //Clear any unwanted data contained in the shift registers
}

void loop()
{
    getDateDs1307(); //Get current time from RTC
    clear_shift_regs(); //Clear anything currently in the shift registers
    if(hour > 12) hour -= 12; //If decimal hour returned > 12, subtract 12 to only display
    12-hour time format
    if(hour == 0) hour = 12; //If decimal hour returned == 0, it is 12 AM

    //Serial.println(hour,BIN); // DEBUG
    hour = decToBcd(hour); //Convert the decimal hour to BCD -- Ex. 12 (dec) = 0x12 (hex-BCD) =
    0001 0010 (bin-BCD)

    shift_number_in(hour>>4, hour&0x0F, minute>>4, minute&0x0F); //Parallel shift of current time
    digits into shift registers

    delay(30000); //Wait 30 seconds before updating again to prevent flicker...
}

//Function: shift_number_in ( hour_high_digit, hour_low_digit, minute_high_digit,
minute_low_digit )
void shift_number_in(int hour_hi, int hour_lo, int min_hi, int min_lo)
{
    //Shift in seven bits to each shift register. Output of shift registers is hooked up to 7-segs.
    for(int i = 0; i<7; i++)

```

```

{
    digitalWrite(HR_HI, digit_map[hour_hi][i]);
    digitalWrite(HR_LO, digit_map[hour_lo][i]);
    digitalWrite(MI_HI, digit_map[min_hi][i]);
    digitalWrite(MI_LO, digit_map[min_lo][i]);

    //Clock this data in
    digitalWrite(clk, HIGH);
    delayMicroseconds(3);
    digitalWrite(clk, LOW);
}

}

//Function: clear_shift_regs()
//Send a reset to the shift registers to eliminate any registered data
void clear_shift_regs()
{
    digitalWrite(rst,LOW); //active low reset
    delayMicroseconds(1); //The required pulse width for reset to work is in 10's to 100's of ns
    range. 1-3 uS should be plenty
    digitalWrite(rst,HIGH); //disable reset
}

// Gets the date and time from the ds1307
void getDateDs1307()
{
    // Reset the register pointer
    Wire.beginTransmission(DS1307_I2C_ADDRESS); //Start transmission
    I2C_WRITE(zero); //Write 0x00 to register pointer (points to register to read in RTC memory
    space)
    Wire.endTransmission(); //End transmission

    Wire.requestFrom(DS1307_I2C_ADDRESS, 3); //Start a transaction to read 7 bytes from the RTC
    starting at RTC register 0x00 (set in previous command)

    second = bcdToDec(I2C_READ() & 0x7f); //MSB is a Clock Halt bit. Mask this off.
        //Seconds in format S7 S6 S5 S4 S3 S2 S1
        //S7-S5 represents 10's of seconds (ex. 40 seconds
        would be 010)
        //S4-S1 represents 1's of seconds (ex. 5 seconds would
        be 0101)
    minute = I2C_READ(); //Minutes in format M8 M7 M6 M5 M4 M3 M2 M1
        //M8 is always 0
        //M7-M5 represents 10's of minutes
        //M4-M1 represents 1's of minutes

    hour = bcdToDec(I2C_READ() & 0x3f); //Hours in format H8 H7 H6 H5 H4 H3 H2 H1
        //H8 is always 0 -- masked here
        //H7 Indicates 12 hour or 24 hour format -- configure
        this for 24 hour - This bit set LOW
        //H6-H5 Indicates 10's of hours -- (ex. 12:00 would be

```

```
        represented as 01 (bin), 24:00 would be represented as 10
        (bin))
        //H4-H1 Indicates 1's of hours -- (ex. 5:00 would be 0101
        (bin), 13:00 would be 0011)
    }

//Converts a decimal number to a BCD number
byte decToBcd(byte val)
{
    return ( (val/10*16) + (val%10) );
}

// Convert binary coded decimal to normal decimal numbers
byte bcdToDec(byte val)
{
    return ( (val/16*10) + (val%16) );
}
```