

Lead Screw Test

Date Completed: _____

Performed By: _____

Specifications Tested

#	Specification	Unit of Measure	Target Value	Comments
S5	Limits of travel in each direction	cm	1	Specification is provided for range of motion of the manipulator. In order for the manipulator to achieve 1cm of motion the lead screw need to travel 2.3 cm.
S6	Speed of travel	mm/s	0.5	Motor rated at 22rpm. Theoretical max speed is 0.116 mm/s
S7	Resolution	μm	< 0.1	The resolution of the lead screw must be 0.23 μm in order for the manipulator to obtain a resolution of 0.1 μm .
S8	System backlash	rev	< 1	Theoretically there should be no backlash at the lead screw. The majority of the backlash introduced in the hydraulic system.
S13	Systems full range of motion can be operated in safely	Binary	Yes	

Document History

Revision	Description	Date
1	Document Created	10/28/2012

Equipment

- ___ Lead screw and motor assembly
- ___ Power supply for controls and motor
- ___ Computer to control motor
- ___ Stop watch
- ___ Ruler
- ___ Micrometer

Sections (Can be completed and combined as necessary)

- Part I: Limits of travel, speed of travel and safe operation
- Part II: System backlash and drift
- Part II: Resolution

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Part I: Limits of travel and safe operation

_____ 1. Attach lead screw to motor coupling

_____ 2. Move lead screw nut to the furthest rear position (motor-side)

_____ 3. Mark position of lead screw nut

_____ 4. Move lead screw nut to furthest forward position and use the stop watch to find the time it takes to complete the full distance.

_____ 5. Mark position of lead screw nut and measure the distance between the start and end position

_____ 6. Repeat for all axes

Measurement	Units	Value
Distance between start and end position	mm	

Sign off on section completion before continuing: _____

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Part II: System backlash

- _____ 1. Mark initial position of lead screw nut
- _____ 2. Move lead screw forward ten revolutions
- _____ 3. Move lead screw backward ten revolutions
- _____ 4. Mark end position of lead screw nut
- _____ 5. Calculate the degrees of backlash and repeat for all the axes

Measurement	Units	Value
Backlash	Degrees	

Sign off on section completion before continuing: _____

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Part III: Resolution

- _____ 1. Move lead screw nut backwards till backlash is eradicated
- _____ 2. Mark position of lead screw nut
- _____ 3. Rotate motor full 20 revolutions to move lead screw backwards
- _____ 4. Mark position of lead screw nut and measure the distance between the start and end position

Measurement	Units	Value
Distance between start and end position	mm	

Sign off on section completion before continuing: _____

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Part IV: Speed of Travel

_____ 1. Mark initial position of lead screw nut

_____ 2. Time the motors running at max. speed for 10 revolutions

_____ 3. Mark final position of lead screw nut

Measurement	Units	Value
Speed of travel	mm/s	

Sign off on section completion before continuing: _____